## B. V. Boshenyatov and B. I. Zaslavskii

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The problem of the reflection of a cylindrical shock wave in water from the free surface is analyzed within the framework of shortwave theory [1, 2]. The motion is studied essentially on the basis of results obtained in [2-4].

1. Let a shock wave be generated by an explosion of an infinite cylindrical charge, per unit length of which a certain energy, characterized by the linear dimension $\mathrm{R}_{0}$ (the charge radius), is released. The axis of the charge is parallel to the free surface at a certain depth $h$. We align the axis of the cylindrical system of coordinates $r, \theta$ with the charge axis. The angle $\theta$ will be laid off from a plane parallel to the free surface. The flow behind the shock wave front will be determined on the basis of the system of "shortwave" equations [1, 2]

$$
\begin{gather*}
\frac{\partial \mu}{\partial \tau}+(\mu-\delta) \frac{\partial \mu}{\partial \delta}+\frac{1}{2} \frac{\partial v}{\partial y}+\frac{1}{2} \mu=0 \\
\frac{\partial v}{\partial \delta}-\frac{\partial \mu}{\partial y}=0 \tag{1.1}
\end{gather*}
$$

The quantities $\mu, \nu, y, \delta$ are defined by the equalities

$$
\begin{gathered}
U=a_{0} M_{0} \mu, \quad V=a_{0} M_{0} \sqrt{\frac{n+1}{2} M_{0}} v, \\
r=a_{0} t\left(1+\frac{n+1}{2} M_{0} \delta\right), \quad \tau=\ln \frac{a_{0} t}{R_{0}}, \\
0=y \sqrt{\frac{n+1}{2} M_{0}}, \quad M_{0} \mu=\frac{p}{B n}, \quad R=\frac{r}{R_{0}}, \\
b=3045 \mathrm{~atm}, \quad n=\mathbf{7 . 1 5},
\end{gathered}
$$

where $a_{0}$ is the initial speed of sound; $U$ and $V$ are the projections of the particle velocity vector on the direction of radius vector, and on the direction normal to it , respectively; $\mathrm{M}_{0}$ is a certain small quantity; and $R$ is a distance expressed in terms of the charge radius $R_{0}$.

From (1.1) it is possible to obtain the flow which forms behind the shock wave front in an unbounded fluid, in which case $\nu=0$, i. e., the flow is one dimensional [2]. We get

$$
\begin{equation*}
\delta=2 \mu+e^{-\tau} \Phi\left(\mu^{2} e^{\tau}\right) \tag{1.2}
\end{equation*}
$$

where $\Phi$ is an arbitrary function. In the following, we assume that the pressure profile behind the shock front is triangular; then

$$
\begin{equation*}
\delta=2 \mu+C e^{-\tau} \tag{1.3}
\end{equation*}
$$

The position of the snock front is defined by the equation

$$
\begin{equation*}
\delta+\frac{\partial \delta}{\partial \tau}=\frac{1}{2} \mu+\frac{1}{2}\left(\frac{\partial \delta}{\partial y}\right)^{2} \tag{1.4}
\end{equation*}
$$

In the one-dimensional case, from (1.4) and (1.3), at the shock front, we get

$$
\begin{equation*}
\mu=A e^{-3 \tau / 4}, \quad \delta=2 A e^{-3 \tau / 4}+C e^{-\tau} \quad(A, C=\text { const }) \tag{1.5}
\end{equation*}
$$

From (1.5) and (1.1), there follows Landau's [5] asymptotic formula

$$
\begin{equation*}
P=k R^{-3 / 4} \quad(k=\text { const }) . \tag{1.6}
\end{equation*}
$$

2. After the shock wave reaches the free surface, the rarefaction waves which propagate from the points of the free surface through which the shock front has passed interact with the flow (1.3). In the determination of the flow in the interaction region (which we term the disturbed flow), it is convenient to place the origin O of the system
of coordinates on the free surface, at the point $\mathrm{O}_{1}$ of intersection with the normal to the center of the charge (Figure 1). The transformation formulas from $\mu, \nu, \mathrm{y}, \delta$ to $\mu_{1}, \nu_{1}, \mathrm{y}_{1}, \delta_{1}$ in the new system of coordinates have the form

$$
\begin{gather*}
\delta={ }^{2 \tau}+y_{1} y_{0} e^{-\tau}, \quad v_{1}=v-\mu y_{0} e^{-\tau} \\
y_{1}=y+y_{0} e^{-\tau}, \mu_{1}=\mu \\
\left(y_{0}=\frac{h}{R_{0} \sqrt{1 / 2}(n+1) M_{0}}\right) \tag{2.1}
\end{gather*}
$$

We perform the following change of variables and functions:

$$
\begin{gather*}
\delta_{1}=\left[\delta^{\circ}+\delta_{0}(\tau)\right] e^{-1 / 2 \tau}, \quad y_{1}=y^{\circ} e^{-\tau / 4} \\
\mu_{1}=\left[\mu^{\circ}+\mu_{0}(\tau)\right] e^{-1 / 2 \tau}, \quad v_{1}=\left(v^{0}+2 y^{\circ} \frac{d \mu_{0}}{d \tau}\right) e^{-3 / \ell^{\tau}} \tag{2.2}
\end{gather*}
$$

Here, $\delta_{0}(\tau)$ and $\mu_{0}(\tau)$ are unknown functions of time, $\delta_{0} e^{-\tau / 2}$ is the value of $\delta_{1}$ at point $A$ of intersection of shock wave front and free surface, and $\mu_{0} \mathrm{e}^{-\tau / 2}$ is the value of $\mu_{1}$ and at this point. After performing transformations (2.2), Eqs. (1.1) take the form

$$
\begin{gather*}
\frac{\partial \mu^{\circ}}{\partial \tau}+\left(\mu^{\circ}+\mu_{0}-\frac{\delta^{\circ}+\delta_{0}}{2}-\frac{d \delta_{0}}{d \tau}\right) \frac{\partial \mu^{\circ}}{\partial \delta^{\circ}}+ \\
\frac{1}{4} y^{\circ} \frac{\partial \mu^{\circ}}{\partial y^{\circ}}+\frac{1}{2} \frac{\partial v^{\circ}}{\partial y^{\circ}}=0, \quad \frac{\partial \mu^{\circ}}{\partial y^{\circ}}-\frac{\partial v^{\circ}}{\partial \delta^{\circ}}=0 \tag{2.3}
\end{gather*}
$$

3. The reflection of a shock wave from the free surface can involve regular and irregular reflections [3]. An irregular reflection starts from the instant the rarefaction waves propagating from the free surface catch up with the shock front. Assume that this instant is reached at a distance $R=\mathbf{R}_{*}$ or correspondingly, $\tau=\tau_{*}$. At the shock wave front, we set

$$
\begin{equation*}
\mu_{0}\left(\tau_{*}\right)+\mu^{\circ}=1 \tag{3.1}
\end{equation*}
$$

The value of $y_{0}$ and $M_{0}$ can be expressed through $\tau_{*}$ [4],

$$
\begin{equation*}
y_{0}=e^{3_{1} \tau_{*}}, \quad M_{0}=\frac{k}{B n} e^{-1_{1} \tau_{*}} \tag{3.2}
\end{equation*}
$$

Formulas (1.1), (2.1). (1.6) are used in the derivation of (3.2). In the new system of coordinates, Eqs. (1.3) and (1.5) take the form

$$
\begin{gather*}
\delta^{\circ}=2\left(\mu_{0}+\mu^{\circ}\right)-1 / 2^{-3}+y^{0} x^{-3 / 2}-3 / 2 x^{-1}-\delta_{0}(\tau)  \tag{3.3}\\
\delta^{\circ}+\delta_{0}=2 x^{-1 / 2}-3 / 2 x^{-1}+y^{\circ} x^{-3 / 2}-1 / 2 x^{-3} \\
\left(\mu^{\circ}+\mu_{0}=x^{-1 / 2}, \quad x=e^{1 / 2 \div-\tau} *\right) \tag{3.4}
\end{gather*}
$$

The perturbed-flow region contacts flow (3.3) along the characteristic surface of Eqs. (2.3) (BD in Fig. 1). The equation of the characteristic surface of Eqs. (2.3) has the form

$$
\begin{gather*}
-\frac{\partial \delta^{\circ}}{\partial \tau}+\left(\mu^{\circ}+\mu_{0}-\frac{1}{2} \delta^{\circ}-\frac{1}{2} \delta_{0}-\frac{d \delta_{0}}{d \tau}\right)- \\
\frac{1}{4} y^{\circ} \frac{\partial \delta^{\circ}}{\partial y^{\circ}}+\frac{1}{2}\left(\frac{\partial \delta^{\circ}}{\partial y^{\circ}}\right)^{2}=0 \tag{3.5}
\end{gather*}
$$

By integrating (3.5), under the condition that the required sur face extend along (3.3) and that it pass through point A at time $\tau=\tau_{*}$, we get

$$
\begin{equation*}
\delta^{\circ}=q_{0}(\tau) y^{02}+\chi_{1}^{\nu}(\tau) y^{\circ}+\chi_{0}^{\nu}(\tau), \tag{3.6}
\end{equation*}
$$



Fig. 1

$$
\begin{gather*}
q_{0}=-1 / 4 \quad(x-1)^{-1}, \quad \chi_{1}^{\nu}=-1 / 2^{-3} x^{3}(x-1) \\
\chi_{0}{ }^{\nu}=-1 / 4 x^{-3}+1 / 4 x^{-2}-7 / 4 x^{-1}+7 / 4-\delta_{0}(\tau) \tag{3.7}
\end{gather*}
$$

The point of intersection B (Fig. 1) of the characteristic surface $B D$ and the shock front separates the segment of the front $A B$ which is distorted by the influence of the free surface from the undistorted portion of the shock front. The coordinates of this point are determined from (3.4) and (3.6),

$$
\begin{gather*}
y_{B}{ }^{\circ}=-x^{-9 / 2}\left(x^{2}-1\right)+ \\
+\left[x^{-1}\left(x^{2}-1\right)-4(x-1)\left(2 x^{-1 / 2}+1 / 4 x^{-1}-7 / 0\right)\right]^{1} 2 \\
\delta_{B}^{\circ}=q_{0} y_{B}^{02}+\chi_{1} v^{0} y_{B}^{0}+\chi_{0}{ }^{0} \tag{3.8}
\end{gather*}
$$

In this way, the solution is sought in a region bounded by the free surface, the segment of the shock front $A B$ and the characteristic surface $B D$. Near the point of intersection ( $A$ ) of the shock front and the free surface, there occurs a Prandtl Meyer type flow [3], i.e., for $y^{0} \rightarrow 0, \delta \rightarrow 0$,

$$
\begin{equation*}
\mu^{\circ}=-\frac{1}{2}\left(\frac{\delta^{\circ}}{y^{\circ}}\right)^{2}+\mu_{0}(\tau), \quad v^{\circ}=\frac{1}{3}\left(\frac{8^{\circ}}{y^{\circ}}\right)^{3}+v_{0}(\tau) \tag{3.9}
\end{equation*}
$$

Formulas (3.9) are the boundary conditions at the free surface. At the shock front, whose equation in $\delta^{\circ}, y^{0}, \tau$ coordinates is of the form

$$
\begin{gather*}
\frac{\delta_{0}+\delta^{\circ}}{2}+\frac{\partial \delta^{\circ}}{\partial \tau}+\frac{d \delta_{0}}{d \tau}+\frac{1}{4} y^{\circ} \frac{\partial \delta^{\circ}}{\partial y^{\circ}}= \\
\frac{1}{2}\left(\mu_{0}+\mu^{\circ}\right)+\frac{1}{2}\left(\frac{\partial \delta^{\circ}}{\partial y^{\circ}}\right)^{2} \tag{3.10}
\end{gather*}
$$

it is necessary to fulfill the condition for the continuity of the velocity vector component tangential to the shock front

$$
\begin{equation*}
\left(\mu^{\circ}+\mu_{0}\right) \frac{\partial \delta^{\circ}}{\partial y^{\circ}}+v^{\circ}=0 \tag{3.11}
\end{equation*}
$$

For irregular reflection, at point $A$, the angle of incidence of the shock wave $\alpha$ (i.e., the angle formed by the shock front and the normal to the free surface) always retains its critical value $[3,4]$, i.e.,

$$
\begin{equation*}
\alpha=\left(\frac{n+1}{2} \frac{p^{\prime}}{B n}\right)^{1 / 2}=\alpha_{0}\left(\frac{n+1}{2} M_{0}\right)^{1 / 2} e^{-1 / 4 \tau}, \tag{3.12}
\end{equation*}
$$

where $p^{\prime}$ is the pressure at the shock front at point A. From here, in $\delta^{0}, y^{0}, \tau$ coordinates, we get

$$
\begin{equation*}
\alpha_{*}^{\circ}=\left.\frac{\partial \delta^{\circ}}{\partial y^{\circ}}\right|_{y=0}=\sqrt{\mu_{0}(\tau)} \tag{3.13}
\end{equation*}
$$

and, consequently,

$$
\begin{equation*}
\mu_{0}=\frac{d \delta_{0}}{d \tau}+\frac{1}{2} \delta_{0} . \tag{3.14}
\end{equation*}
$$

At the characteristic surface $E D$, the flow to be determined must contact (3.3).
4. In order to determine the flow in region $A B D$, we use the exact particular solutions of system (2.3), obtained in [4]:

$$
\mu^{\circ}=\varphi_{2} y^{\circ 2}+\varphi_{1} y^{\circ}+\varphi_{0}
$$

$$
\begin{gather*}
v^{\circ}=\psi_{3} y^{03}+\psi_{2} y^{\circ 2}+\psi_{1} y^{0}+\psi_{0}, \\
\delta^{\circ}=q y^{02}+\chi_{1} y^{0}+\chi_{0}, \quad \varphi_{2}=-1 / 2 q^{2}+1 / 2 q+z(\tau), \\
\psi_{3}=-2 / 3\left[\varphi_{2 \tau}+\varphi_{2 q}\left(\varphi_{2}-q+2 q^{2}\right)+1 / 2 \varphi_{2}-2 \varphi_{2} q\right], \\
\psi_{2}=-\varphi_{1}=-\varphi_{1 q}\left(\varphi_{2}-q+2 q^{2}\right)+\chi_{1} \varphi_{2}+\varphi_{1} q-1 / 4 \varphi_{1}, \\
\psi_{1}=-2 \varphi_{0 \tau}-2 \varphi_{0 q}\left(\varphi_{2}-q+2 q^{2}\right)+\varphi_{1} \chi_{1}, \\
\psi_{0}=\varphi_{1} \chi_{0 q}-\chi_{1} \varphi_{0 q}, \\
\chi_{1}=\int\left(\int_{-\infty}^{q)} w d q\right) d q, \quad \chi_{0}=\int_{-\infty}^{q} v d q, \\
-\infty  \tag{4.1}\\
\varphi_{1}=\int_{-\infty}^{q} \varphi_{2 q}\left(\int_{-\infty} w d q\right) d q, \varphi_{0}=\int_{-\infty}^{q} \varphi_{2 q} v d q .
\end{gather*}
$$

The functions $w$ and $v$ are determined from the equations

$$
\begin{gather*}
w_{\tau}+w_{q}\left(3 / 2 q^{2}-1 / 2 q+z\right)+w(5 q-3 / 4)=0 \\
v_{\tau}+v_{q}\left(3 / 2 q^{2}-1 / 2 q+z\right)+v(4 q-1 / 2)-\chi_{1} \chi_{1 q}=0 \tag{4.2}
\end{gather*}
$$

Solutions (4.1) satisfy (3.9) for any finite values of $z(\tau), v(q, \tau)$, and, $\mathrm{w}(\mathrm{q}, \tau)$. We select these functions from the condition for the flow (4.1) to contact flow (3.3) at characteristic surface $B D_{9}$ at which $q=q_{0}(\tau)$.

We write (3.3) in the following way:

$$
\begin{gather*}
\mu^{\circ}=1 / 2 q y^{\circ 2}+\varphi_{1}{ }^{\nu} y^{\circ}+\varphi_{0}{ }^{\nu}, \delta^{\circ}=q y^{\circ 2}+\chi_{1}{ }^{\nu} y^{\circ}+\chi_{0}{ }^{\nu},  \tag{4.3}\\
\nu=-\left(\mu^{\circ}+\mu_{0}\right) x^{-8 / 8}+2 \mu_{0}{ }^{\circ} e^{8 / / \sigma_{*}} \\
\varphi_{1}{ }^{\nu}=-1 / 4 x^{-2 / 2}(x+1) \\
\varphi_{0}{ }^{\nu}=1 / 8 x^{-3}+1 / 8 x^{-2}+1 / 8 x^{-1}+1 / 8-\mu_{0}(\tau) \tag{4.4}
\end{gather*}
$$

In order that (4.1) convert to (4.3) at characteristic curve BD the functions must satisfy the following conditions:

$$
\begin{gather*}
\varphi_{2}\left(q_{0}, \tau\right)=1 / 2 q_{0}, \quad z(\tau)=1 / 2 q_{0}{ }^{2} \\
\chi_{1}\left(q_{0}, \tau\right)=\chi_{1}{ }^{\nu}, \quad \chi_{0}\left(q_{0}, \tau\right)=\chi_{0}^{\nu}  \tag{4.5}\\
\varphi_{1}\left(q_{0}, \tau\right)=\varphi_{1}{ }^{\nu}, \varphi_{0}\left(q_{0}, \tau\right)=\varphi_{0}{ }^{\nu} \\
\psi_{0}\left(q_{0} \tau\right)=-\left(\varphi_{0}{ }^{\nu}+\mu_{0}\right) x^{-1 / 2} \\
\psi_{1}\left(q_{0}, \tau\right)=2 \mu_{0}{ }^{\prime}-\varphi_{1}{ }^{\nu} x^{-1 / 4} \\
\psi_{2}\left(q_{0}, \tau\right)=-1 / 2 q_{0} x^{-2 / 2}, \quad \psi_{3}\left(q_{0}, \tau\right)=0 \tag{4,6}
\end{gather*}
$$

Fulfillment of (4.5) means also the fulfillment of (4.6). In this way, the problem reduces to the integration of the two equations (4.2) for condition (4.5). The general solution of these equations has the form

$$
\begin{gather*}
w=F_{1}(\eta) x^{3 / 2} \omega^{6 / 3}(\omega-3 \eta)^{10 / 3} \\
v=x \omega^{6 / 3}(\omega-3 \eta)^{3 / 3} \times \\
\times\left[\omega^{4}+8 \eta \omega^{3}-26 \eta^{2} \omega^{2}-168 \eta^{3} \omega+F_{2}(\eta)\right] \\
\eta=\omega \frac{1+4(x-1) q}{1+1^{2}(x-1)}, \omega=\sqrt{\frac{x-1}{x}} \tag{4,7}
\end{gather*}
$$

where $F_{1}$ and $F_{2}$ are arbitrary functions. From condition (4.7), we have

$$
\begin{gather*}
z(\tau)=-1 / 2 q_{0}{ }^{2}, \quad \varphi_{2}(q, \tau)=-1 / 2 q^{2}+1 / 2 q+1 / 2 q_{0}^{2}, \\
\int_{-\infty}^{q_{0}}\left(\int_{-\infty}^{q_{0}} w_{1} d q\right) d q=\chi_{1}\left(q_{0}, \tau\right)=-\frac{1}{2} x^{-\frac{1}{2}}(x-1) \tag{4.8}
\end{gather*}
$$

From here we find

$$
\begin{gather*}
F_{1}=-280 \eta \\
\chi_{1}=\int_{-\infty}^{q}\left(\int_{-\infty}^{q} w d q\right) d q=-\frac{(\omega+2 \eta)}{\left.2 x^{1 / 2} \omega\right)^{1 / 3}}(\omega-3 \eta)^{1 / 3} \\
\varphi_{1}=-\frac{(x-1)(2 \eta+\omega)}{4 x^{3 / 2} \omega^{2 / 3}}(\omega-3 \eta)^{4 / 3}+ \\
+\frac{(\eta+\omega)(\eta-2 \omega)}{4 x^{3 / 2} \omega^{7 / 2}}(\omega-3 \eta)^{1 / 3} \tag{4,9}
\end{gather*}
$$

For determining $\mathrm{F}_{2}$, we have

$$
\begin{equation*}
\chi_{0}{ }^{\nu}(\tau)=\int_{-\infty}^{q_{2}} v d q=\frac{13}{220} \omega^{6}-\frac{1}{2} \omega^{1 / 3} \int_{1 / 3 \omega}^{0} F_{2}(\eta)(\omega-3 \eta)^{2 / 3} d \eta,(4 \tag{4.10}
\end{equation*}
$$

or, after simple transformations

$$
\begin{gather*}
\int_{1 / 3 \omega}^{n} B(\eta)(\omega-3 \eta)^{2 / 3} d \eta=2 \omega^{-1 / 4}\left[1 / 4 \omega^{6}-1 / 4 \omega^{4}+2 \omega^{2}-\delta_{0}(\tau)\right] \\
B(\eta)=F_{2}+1547 / 3 \eta^{4} \tag{4.11}
\end{gather*}
$$

5. After substitution of (3.14), the equation for the shock wave front has the form

$$
\frac{1}{2} \mu_{0}(\tau)+\frac{\partial \delta^{\circ}}{\partial \tau}+\frac{1}{4} y^{\circ} \frac{\partial \delta^{\circ}}{\partial y^{\circ}}-\frac{1}{2} \mu^{\circ}-\frac{1}{2}\left(\frac{\partial \delta^{\circ}}{\partial y^{\circ}}\right)^{2}=0,(5.1)
$$

where the function $\mu_{0}(\tau)$ is determined from the condition at the front, at the point $y^{0}=0$

$$
\begin{equation*}
\delta(0, \tau)=0 \tag{5.2}
\end{equation*}
$$

This function can be determined numerically in the same manner that a similar function was determined in [4]. If the function $\delta_{0}(\tau)$; related to $\mu_{0}(\tau)$ by relation (3.14), is approximated within the range $\boldsymbol{\tau}_{0}<\boldsymbol{\tau}<\boldsymbol{\tau}_{1}$ by a polynomial, i. e. , if one sets

$$
\delta_{0}=a_{0}+a_{1} \omega+a_{2} \omega^{2}+\ldots
$$

then the functions $\varphi_{0}(q, \tau)$ and $\chi_{0}(q, \tau)$ will be expressed by finite formulas which contain the unknown coefficients $a_{k}$. These coefficients
must be determined in such a way that condition (5.2) is satisfied with the greatest possible accuracy within the given range.

$$
\delta(0, \tau)=0
$$

Because of their bulkiness, the formulas for $\varphi_{0}(\mathrm{q}, \tau)$ and $\chi_{0}(\mathrm{q}, \tau)$ are not presented.

The solution obtained satisfies all the boundary conditions of the problem, except the condition for the continuity of the velocity vector component tangential to the shock front (3.11). Within the class of particular solutions (4.1), this condition can be satisfied only approximately.

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